# Safety Technique

# SAFEMASTERS Speed Monitor UH 5947

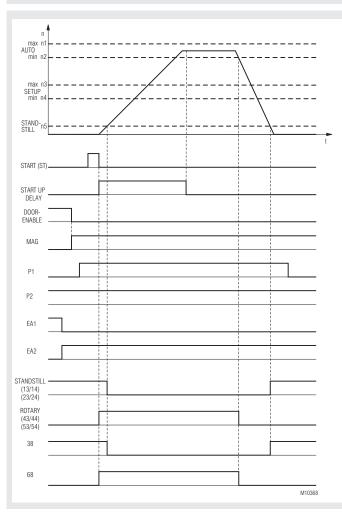




# **Product Description**

The speed monitor UH 5947 provides safe monitoring of motors and rotating equipment. It is used in machines and plants where machine movements or moving parts can be a danger to men and machine. Using the front side display the parameters can be easily and comfortably adapted to the individual application or changed when necessary.

# **Function Diagram**



# Your Advantages

#### Three in one

- safe speed monitoring in automatic and set up operation
  safe standstill monitoring
- safe integrated gate monitoring
- For safety applications up to PL e / Cat 4 and SIL 3
- Space and costsaving, no external safe gate monitoring required
- Simple and time saving setup without PC
- Comfortable, menu guided configuration via frontside display
- Reducing interruption time in production by extensive diagnostic functions
- Easy to integrate in existing drive applications
- · Suitable for all common motor feedback systems and proximity sensors
- Copy parameter settings in other units by pressing only a push button
- Higer safety by 2-channel mode selector, external connection
- With adjustable ratio between 2 sensors e.g. to detect a broken shaft
- Possible languages: english, german, french, italian, spanish

#### Features

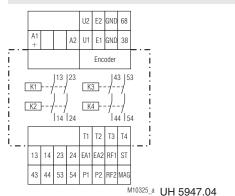
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- · According to
  - Performance Level (PL) e und category 4 to EN ISO 13849-1: 2008
     SIL-Claimed Level (SIL CL) 3 to IEC/EN 62061
  - Safety Integrity Level (SIL 3) to IEC/EN 61508
- According to EN 60204
- Device setting on menu-driven display or via RJ45 (FCC Western-Modular 8P8C) with connection cable (copy function)
- Change tracking
- Adjustable operation mode
  - Automatic mode: Monitoring of automatic rotational speed window and standstill speed.
  - Setup mode: Monitoring of setup rotational speed window. Standstill is permanently enabled.
- Single or 2-channel safety gate monitoring
- Integrated user friendly display for parameters and operation status
   for set point and actual value of U/min or m/min
  - set point display also as frequency value
  - with numerous diagnostic features
- Adjustable start up delay (0 ... 999 s)
- Adjustable time delay for standstill detection (13/14, 23/24) (0 ... 999 s)
- Adjustable monitoring time for feedback circuit RF1 (0,5 ... 999 s)
- Monitoring of an release magnet
- Monitoring of feedback circuits
- Activation of the output path 43/44, 53/54 with on/off pushbutton with short circuit detection or automatic making function
- Adjustable PNP- or NPN-sensors
  - Connection of different encodern possible (sin/cos, TTL, HTL)
  - 2-channel function
  - Forcibly guided contacts
  - · LED-indicators and 2 semiconductor monitoring output
  - With pluggable terminal blocks for easy exchange of devices
    - with screw terminals
    - or with cage clamp terminals
  - Width 45 mm

# **Approvals and Markings**



### **Circuit Diagram**



#### **Connection Terminals**

Terminal designation	Signal designation
A1 (+)	+/L
A2	- / N
U1, U2	+ supply for proximity sensors or NAMUR-sensors
GND	- supply for proximity sensors
E1, E2	Input for pulse signal from proximity sensors or NAMUR-sensors
13, 14, 23, 24, 43, 44, 53, 54	Forcibly guided NO contacts for release circuit
38, 68	Semiconductor-monitoring output
T1, T2, T3, T4	Control output
ST, MAG, RF1, RF2, P1, P2, EA1, EA2	Control input

#### Application

This device is designed for machinery and installations where hazards to people and property may be caused by the movement of machines or parts.

The device permanently monitors for standstill (output circuit 13/14, 23/24) and rotational speed (output circuit 43/44, 53/54). For the rotational speed monitoring, it is possible to choose between automatic and setup mode. If properly connected, the UH5947 can be used to implement the safety functions STO (safe torque off), SOS (safe operation stop), SLS (safely limited speed), SSM (safe speed monitoring), SSR (safe speed range), as well as SDL (safe door locking) as per standard EN 61800-5-2.

#### **Functions**

The device can be configured from the display and keys on the front plate or via RJ45 using a suited connection cable (see accessories) by means of the copy function.

Following measuring sensors can be used to sense the rotational speed:

- · Two NPN or PNP proximity sensors (special version with NAMUR sensors) connected to the inputs E1 and E2. The proximity sensors (NAMUR sensors) are supplied with 24VDC from the speed relay to the terminal U1 and U2 (special version NAMUR 8.2V DC).
- Encoders (sin/cos, TTL, HTL) connected to the RJ45 interface via cable adapter (optionally available). The powersupply for the encoder is not provided by the speed monitor. Feedback influences should not occur.
- Combination from encoder and one proximity or NAMUR sensor for special version.

Indicator		
DEVICE:	green-flashing - red-flashing -	<ul> <li>→ Run</li> <li>→ Parameterization mode</li> <li>→ Parameterization error</li> <li>→ Device fault</li> </ul>
K1/K2:	0	<ul> <li>→ Output contact 13/14, 23/24 closed</li> <li>→ Stop monitoring feedback loop 2 failed</li> </ul>
K3/K4:	0	<ul> <li>→ Output contact 43/44, 53/54 closed</li> <li>→ Stop monitoring feedback loop 1 failed</li> </ul>
SF:		<ul> <li>→ no failure</li> <li>→ (external) failure</li> </ul>
DISPLAY:	-	<ul> <li>→ Status indication</li> <li>→ Alarms / diagnostics</li> <li>→ Parameterization</li> </ul>

# Notes

#### **ATTENTION - AUTOMATIC START!**



Input

According to IEC/EN 60 204-1 part 9.2.5.4.2 and 10.8.3 it is not allowed to restart automatically after emergency stop. Therefore the machine control has to disable the automatic start after emergency stop.

# **Technical Data**

input	
Nominal voltage $U_{N}$ :	AC/DC 110 240 V, DC 24 V
Voltage tolerance AC/DC: DC: Nominal frequency (AC): Frequency range (AC): max. residual ripple (DC): Nominal consumption AC/DC:	0.8 1.2 U <sub>N</sub> 0.9 1.1 U <sub>N</sub> 50 / 60 Hz 45 65 Hz 48 %
DC:	< 5 W
Min. Off-time:	150 ms
Measuring accuracy:	± 2 %
Hysteresis:	6.25 %
Initiators	
Input current: Output: Voltage on E1 and E2: Min. pulse duration e. g.	DC 24 V (provided by the device) as option PNP or NPN min. DC 10 V
on and off time:	75 μs
Setting range:	1 Hz 2 kHz
Encoder	
Version:	with 2 signal paths (A, B) and their inverted signals $(\overline{A}, \overline{B}))$
Output:	as option TTL, HTL or sin/cos
	$(U_A = 1 V_{pp})$ When RJ45: Encoder is selected in setup routine under item 1.3 (sensor selection) a defined failure behaviour is necessary (high resistive outputs) in the case of missing
<b>.</b>	powersupply or internal encoder failure. A forced dynamisation (t < 24 h) is necessary during longer standstill periods.
Setting range:	1 Hz 400 kHz

#### **Technical Data**

#### Special Version NAMUR

Supply voltage: Input current: Response value Low: High: Broken wire: Short circuit: Min. pulse duration e. g. on and off time: Setting range:

# Output

Contacts

Contact: Thermal current I<sub>th</sub>:

# Switching capacity

Switching capacity		
to AC 15		
NO contact:	3 A / AC 230 V	IEC/EN 60 947-5-1
to DC 13		
NO contact:	1 A / DC 24 V	IEC/EN 60 947-5-1
to DC 13		
NO contact:	4 A / 24 V at 0.1 Hz	
Electrical life		
at 5 A, AC 230 V cos $\phi$ = 1:	$\geq$ 1 x 10 <sup>5</sup> switching cycle	es IEC/EN 60 947-5-1
Short circuit strength		
max. fuse rating:	4 A gL	IEC EN 60 947-5-1
Mechanical life:	$\geq$ 50 x 10 <sup>6</sup> switching cycles	
Semiconductor		
monitoring output:	2 piece; 20 mA DC 2	4 V, plus switching

max. 5 A

DC 8,2 V (provided by the device)

2 safe relay groups with each 2 NO contacts in series

(see quadratic total current limit curve)

Relay positive guide

max. 10 mA

typ. 1,6 mA

typ. 1,8 mA

≤ 0,15 mA

> 6,0 mA

1 Hz ... 2 kHz

75 μs

#### **Gerneral Data**

Nominal operating mode: continuous operation Temperature range 0 ... + 60 °C Operation: Storage: - 20 ... + 70 °C < 2.000 m Altitude: Clearance and creepage distance rated impulse voltage / 4 kV / 2 IEC 60 664-1 pollution degree: EMC IEC/EN 62 061 interference suppression: EN 55 011 Grenzwert Klasse B Degree of protection: IP 20 IEC/EN 60 529 Housing: thermoplastic with VO behaviour acc. to UL subject 94 Vibration resistance: Amplitude 0,35 mm frequency 10 ... 55 Hz,IEC/EN 60 068-2-6 Climate resistance: 0 / 060 / 04 IEC/EN 60 068-1 **Terminal designation:** EN 50 005 Wire connection: DIN 46 228-1/-2/-3/-4 Plug in with screw terminals max. cross section for connection: 1 x 0,25 ... 2,5 mm<sup>2</sup> solid or stranded ferruled (isolated) or 2 x 0,25 ... 1,0 mm<sup>2</sup> solid or stranded ferruled (isolated) Insulation of wires or sleeve length: 7 mm Terminal block with cage clamp terminals PC 1 x 0.25 ... 2.5 mm2 solid or Cross section: stranded ferruled (isolated) 2 x 0,25 ... 1,5 mm<sup>2</sup> stranded twin ferruled (isolated) Insulation of wires or sleeve length: 10 mm ΡΤ Cross section: 1 x 0.25 ... 1.5 mm<sup>2</sup> solid or stranded ferruled (isolated) Insulation of wires or sleeve length: 8 mm Wire fixing: captive slotted screw or cage clamp terminals Mounting: DIN rail IEC/EN 60 715

approx. 420 g

45 x 107 x 121 mm

# Technical Data

#### Safety Related Data

Values according to EN ISO	13849-1:	
Category:	4	
PL:	е	
MTTF	122	a (year)
DC <sub>avg</sub> :	97,5	%
d <sub>op</sub> :	365	d/a (days/year)
h <sub>op</sub> <sup>cp</sup> :	24	h/d (hours/day)
op t <sub>Zyklus</sub> :	3600	s/Zyklus
Zyklus	≙ 1	/h (hour)
		( )
Values according to IEC EN 6	62061 / IEC EN 6	61508:
SIL CL:	3	IEC EN 62061
SIL	3	IEC EN 61508
HFT <sup>*)</sup> :	1	
DC :	97.5	%
SFF	98,87	%
	98,87 3,02E-09	
DC <sub>avg</sub> : SFF PFH <sub>D</sub> : T,:	,	%
PFH <sub>D</sub> :	3,02E-09	% h <sup>-1</sup>
PFH <sub>D</sub> :	3,02E-09 20	% h <sup>-1</sup>

Info

The values stated above are valid for the standard type. Safety data for other variants are available on request.

The safety relevant data of the complete system has to be determined by the manufacturer of the system.

#### UL-Data

The safety functions were not evaluated by UL. Listing is accomplished according to requirements of Standard UL 508, "general use applications"

Nominal voltage U <sub>N</sub> :	DC 24V AC/DC 110240V (single or double phase) 50 / 60 Hz
Ambient temperature:	0 +60°C
Switching capacity Semiconductor outputs:	24Vdc, 20mA, pilot duty
Switching capacity U <sub>N</sub> = DC 24 V:	Pilot duty B300 5A 250Vac resistive only 2A 24Vdc resistive only
	Device must be supplied with a voltage / current limited power supply (max. 4 A)
Switching capacity $U_N = AC/DC 110 \dots 240 V$ : Ambient temperature 60°C: Ambient temperature 40°C:	Pilot duty B300 2A 250Vac resistive only Pilot duty B300 5A 250Vac resistive only
<b>Wire connection:</b> Plugin screw terminal: Plugin cage clamp terminal: Plugin twin cage clamp terminal:	60°C / 75°C copper conductors only AWG 28 - 12 Sol/Str Torque 0.5 Nm AWG 24 - 12 Sol/Str AWG 24 - 16 Sol/Str



Technical data that is not stated in the UL-Data, can be found in the technical data section.

#### **EAC-Data**

Nominal voltage U<sub>N</sub>: DC 24V

Info

Technical data that is not stated in the UL-Data, can be found in the technical data section.

Dimensions

Weight:

Width x height x depth:

Standard Type		Accessories	
UH 5947.04PS/61 Article number: • Safety output:	DC 24 V 0063476 2 NO contacts for standstill monitoring	OA5947/100:	Connection cable for copy function and adaptor
<ul> <li>Nominal voltage U<sub>N</sub>:</li> <li>Width:</li> </ul>	2 NO contacts for monitoring of speed range (window) DC 24 V 45 mm	KY5947 H1/S1:	15 pole adaptor to connect an encoder or for controllers of Siemens /Heidenhain with corresponding PIN arrangement (see remarks for accessories in operating manual)
Variants		KY5947 H2/S4:	25 pole adaptor to connect an encoder or for controllers of Siemens /Heidenhain with
UH 5947.04/001/61:	NAMUR-version		corresponding PINarrangement (see remarks for accessories in operating manual)
UH 5947.04/101/61:	Sensor selection "E1+E2": The semiconductor outputs give out the	Characteristics	
	incoming signal of E1 with a ratio 1:2. Other sensor selection: The semiconductor outputs have no function.	l² (A²) ▲ 100	
UH 5947.04/200/61:	The transistor outputs 38 and 68 are continuously on when the unit is on operation and are switched off as soon as	80 - 60 - 40 -	
	a failure is detected	20 -	-16 A <sup>2</sup>

Λ

0

30 40

Max. zulässiger Strom bei 60°C über 4 Kontaktreihen = 2A  $\triangleq 4x2^2A^2 = 16A^2$ 

 ${\rm I_1}$  ,  ${\rm I_2}$  ,  ${\rm I_3}$  ,  ${\rm I_4}\text{-}$  Strom in den Kontaktpfaden

10 20

 $I^2 = \ I_1^2 + \ I_2^2 + \ I_3^2 + \ I_4^2$ 

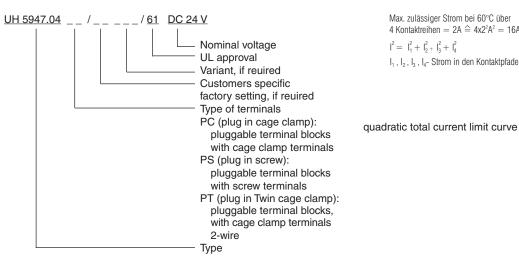
T (°C)

M10484

60

50

# Order reference for variants



**Options with Pluggable Terminal Blocks** 



Screw terminal

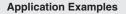


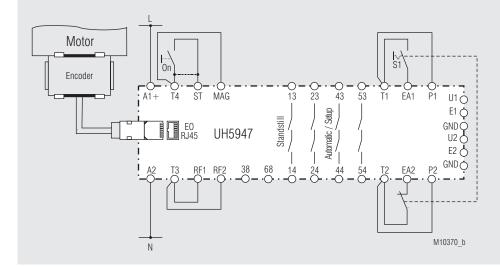
(PS/plugin screw)



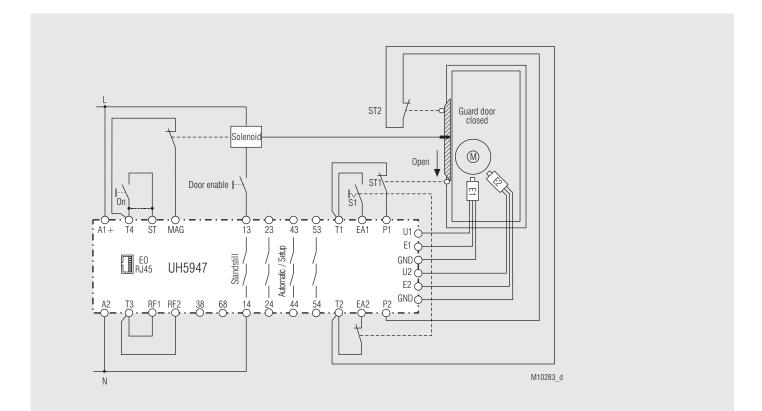
Cage clamp terminal TWIN Cage clamp terminal (PC/plugin cage clamp) (PT/plugin TWIN cage clamp)

09.12.15 en / 619

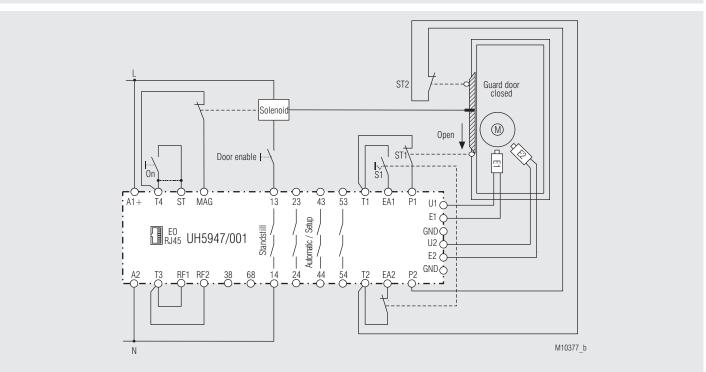




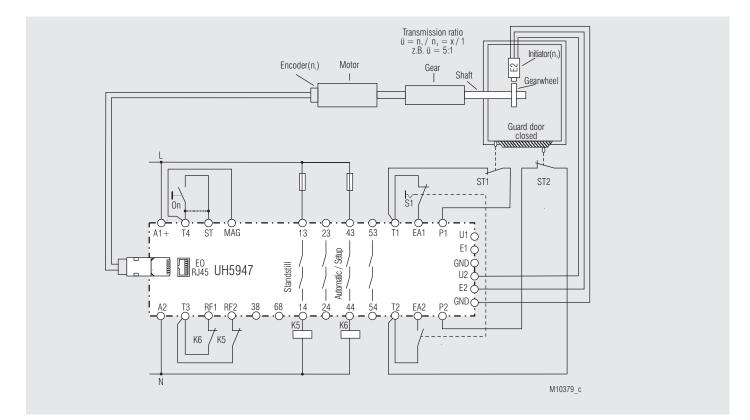
Rotational speed and standstill monitoring with suitable encoder, automatic mode; for manual start: ON/OFF pushbutton to T4/ST; for automatic start: jumper to T4/ST; suited up to SIL3, Performance Level e, Cat. 4 (Requirement for Cat. 4 is, that during longer periods of standstill a forced dynamisation (t < 24 h) has to be carried out).



Two-channel rotational speed and standstill monitoring by means of two NPN or PNP proximity sensors; automatic mode; safety gate monitoring active; for manual start: ON/OFF pushbutton to T4/ST; for automatic start: jumper to T4/ST; suited up to SIL3, Performance Level e Cat. 4 (Requirement for Cat. 4 is, that during longer periods of standstill a forced dynamisation (t < 24 h) has to be carried out).



Rotational speed and standstill monitoring by means of encoder and two NAMUR-sensor; automatic mode; safety gate monitoring active; for manual start: ON/OFF pushbutton to T4/ST; for automatic start: jumper to T4/ST; suited up to SIL3, Performance Level e; Cat. 4



Rotational speed and standstill monitoring by means of encoder and one NPN or PNP proximity sensor; setup mode; gear ratio set; safety gate monitoring active; for manual start: ON/OFF pushbutton to T4/ST; for automatic start: jumper to T4/ST; suited up to SIL3, Performance Level e, Cat. 4 (Requirement for Cat. 4 is, that during longer periods of standstill a forced dynamisation (t < 24 h) has to be carried out).