# **Power Electronics**

# **MINISTART** Softstarter And Softstop Device GF 9016





**Function Diagram** 



# **Block Diagram**





# up to 22 kW

All technical data in this list relate to the state at the moment of edition. We reserve the right for technical improvements and changes at any time.

1

slowly. This reduces the mechanical stress on the machine and prevents damage to conveyed material. When the motor is up to full speed the power semiconductors in GF 9016 are bridged to prevent internal power losses and heat build up. In

Softstarters are electronic devices designed to enable 1-phase or 3-phase induction motors to start smoothly. The GF 9016 slowly ramps up the current on two phases, therefore allowing the motor torque to build up

addition GF 9016 allows a softstop function prolonging the stop time of the motor, preventing high counter torgues from abruptly stopping the motor.

- · For soft and shockfree start of your asynchronous motors
- Less wearing and longer life for your motors and components
- Space saving and easy fitting
- Reduce load from supply mains by reducing of starting current
- According to IEC/EN 60 947-4-2
- Softstart with softstop
- For motors up to 37 kW
- 2-phase control
- Adjustable start up and deceleration time als well as starting voltage, optionally with kickstart
- Without auxiliary voltage
- W3 connection is possible
- As option current control on softstart
- Up to 15 kW: width 45 mm

Motors with gear, belt or chain drive

Start current limiting on 3 phase motors

Packaging machines, door drives

Fans, pumps, conveyor systems, compresseors

Up to 22 kW: width 52.5 mm

# Approvals and Markings



Applications

Function

# Indication

LED green	ON	=	power connected
LED yellow	ON	=	power semiconductors bridged
	flashes stop	s with risir	ng or falling speed at softstart - soft-
	flooboo	with com	a fraguenau at arrar (and table)

flashes with same frequency at error (see table) LED red: On, when failure detected (only on devices  $\geq$  25 kW

# Failure codes up to 22 kW-devices

Fault	LED yellow	Operating state
1	yellow LED flashes 2 x times with short space	device overloaded / heat sink temperature to high
2	yellow LED flashes 3 x times with short space	failure in electronics
3	yellow LED flashes 4 x times with short space	firing error in phase 1
4	yellow LED flashes 5 x times with short space	firing error in phase 3
5	yellow LED flashes 6 x times with short space	error in motor phase/ power semicond. defective in phase 1
6	yellow LED flashes 7 x times with short space	error in motor phase/ power semicond. defective in phase 3
7	yellow LED flashes 8 x times with short space	general synchronising error

# Failure codes from 25 kW-devices

Fault	LED yellow	Operating state
0	yellow LED flashes 1 x times with short space	low supply voltage
1	yellow LED flashes 2 x times with short space	device overloaded / heat sink temp. to high; motor overtemperat.
2	yellow LED flashes 3 x times with short space	current control time out
3	yellow LED flashes 4 x times with short space	phase failure 1
4	yellow LED flashes 5 x times with short space	phase failure 2
5	yellow LED flashes 6 x times with short space	phase failure 3
6	yellow LED flashes 7 x times with short space	frequency failure
7	yellow LED flashes 8 x times with short space	firing error in phase 1
8	yellow LED flashes 10 x times with short space	firing error in phase 3
9	yellow LED flashes 11 x times with short space	mains failure

Motor load must always be connected as continuous operation of the softstart with no load may cause overheating of the motor and softstart. It is recommended that the softstart is protected by superfast semiconductor fuses rated as per the current rating of the softstart or motor. However, standard line and motor protection is acceptable, but for high starting frequencies motor winding temperature monitoring is recommended.

# Technical Data

Nominal voltage:	3 AC (othe	C 400 ers oi	V± <sup>.</sup> n req	I5 % Jest)				
Nominal frequency:	50/60 Hz							
Rated current:	16	25	32	45	50	65	75	А
Nominal motor power at $P_N$ at 400 V:	7.5	11	15	22	25	30	37	kW
Min. motor power:	approx. 0.2 P <sub>N</sub>							
Start torque:	40	. 80 9	%					
Ramp time:	0.5 .	10	s					
Deceleration time:	0.5 .	10	s					
Staring current:	200 with	50 conn	0 % lected	d curr	ent tr	ransfo	ormer	
Recovery time:	200	ms						
Switching frequency:	60	45	35	10	35	25	30	1/ <sub>h</sub>
I <sup>2</sup> t-Power semiconductor fuse	4900	4900	6050	6600	6600	11200	25300	A²s
General Data								
Temperature range:	0	+ 45°	C					
Storage temperature:	- 25	+ 7	70°C					
Overvoltage caregory / polluiton degree:	III / 2	2						
Insulation class:	3							
Peak voltage resistance:	4 kV	'						
Degree of protection:	IP 2	0			I	EC/E	N 60	529
Wire connection								
Load terminals up to 22 kW:	plug	in so	rew t	ermir	nal			
Stranded wire:	6	6	16	16	25	25	25	mm <sup>2</sup>
Control terminals: up to 22 kW: to 25 kW:	1.5 ı 2.5 ı	mm² ( mm² s	cage screw	clam term	p terr ninal	ninals	6	
Mounting:	DIN	rail n	nount	ing	I	EC/E	N 60	715
Weight:	1.0	1.0	1.0	1.0	1.5	1.5	2.2	kg

# Dimensions

# Width x height x depth (incl. terminals)

7,5 / 11 / 15 kW:	45 x 173 x 158 mm
22 kW:	52.5 x 178 x 158 mm
25 / 30 kW:	103 x 230 x 125 mm
37 kW:	103 x 230 x 140 mm

# Standard Type

GF 9016	3 AC 400 V	50/60 Hz	7.5 kW
<ul> <li>Nomina</li> </ul>	al voltage:	3	AC 400 V
<ul> <li>Nomina</li> </ul>	al motor powe	r: 7	.5 kW
• Width:		4	5 mm

#### Ordering Example

<u>GF 9016</u>	3 AC 400 V	50/60 Hz	7.5 kW AC 230 V
			Auxiliary supply (only necessary > 500 V Nominal motor power Nominal frequency Nominal voltage Type

# Accessories

A current transformer for current control on softstart is included in delivery.

# **Control Input**

## Up to 22 kW

Connect conact to X1, X2 and select softstart (close contact) or softstop (open contact). As option the unit can also be started by an external control voltage of DC 10-24 V. This has to be connected to terminals X2, X3, X4 connecting means starting up, disconnection stopping. On terminal X3 a kickstart function can be activated. This is useful on motors that have a high starting load as e.g. mills, breakers, conveyors. Kickstart takes 0.5 sec at fully switched thyristors.

### From 25 kW

- X5, X6: Connection for notor thermistor, must be linked, when not used
- X7. X8: Connection for current transformerm with current control Input is only active, if a current transformer is connected

# **Indicator Outputs**

# Up to 22kW

- error at phase failure, frequency variation, thyristor failure, X5, X6: overtemperature of the unit, disconnected motor. Reset by switching the unit off and on.
- X7, X8: softstart finished, semiconductors bridged.

#### $\ge$ 25 kW

X9, X10:	motor runs, device on operation
X11, X12:	end of softstart, semiconductor bridged
X13, X14:	interference (common alarm)

. . .

Adjustment Facilities					
Potentiometer	Description	Initial setting			
U <sub>start</sub>	Starting voltage	fully anti-clockwise			
t s	Ramp-up time	fully clockwise			
t n	Deceleration time	fully clockwise			
I (only for 25 kW)	current controlled start	fully anti-clockwise			

# Set-up Procedure

Set potentiometer "U<sub>start</sub>" to minimum (fully anti-clockwise). Set potentiometer "t r" to maximum (fully clockwise). Set potentiometer "t  $\gamma$ " to mid position.

Start the motor and turn potentiometer  $"U_{\mbox{\tiny start}}"$  up until the motor starts to turn without excessive humming.

Stop the motor and restart.

Adjust potentiometer "t r" to give the desired ramp time.

Stop and restart the motor.

Adjust potentiometer "t \" to give the desired deceleration time.

Stop and restart the motor, readjusting the potentiometers until the desired starting/stopping characteristics are achieved.

Attention: If the ramp-up time is adjusted to short, the internal bridging ·!`

contact closes before the motor is on full speed.

This may damage the bridging contactor or bridging relay.

#### Safety Notes

Never clear a fault when the device is switched on



Attention: This device can be started by potential-free contact, while connected directly to the mains without contactor (see application example). Please note, that even if the motor is at rest, it is not physically separated from the mains. Because of this the motor *must* be disconnected from the

- mains via the corresponding manual motor starter. - The user must ensure that the device and the necessary components are mounted and connected according to the locally applicable regulations and technical standards.
- Adjustments may only be carried out by qualified specialist staff and the applicable safety rules must be observed.

# **Application Examples**



Softstart with softstop



Softstart in a  $\sqrt{3}$ -circuit up to 22 kW

Start only by connecting the mains voltage, terminals X1-X2 bridget



Softstart and softstop function from 25 kW with controlled current on start up.

E. DOLD & SÖHNE KG • D-78114 Furtwangen • POBox 1251 • Telephone (+49) 77 23 / 654 - 0 • Telefax (+49) 77 23 / 654 - 356