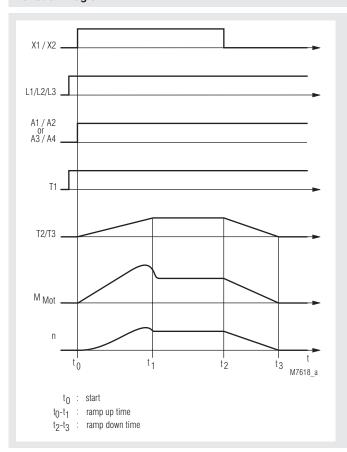


BI 9025 up to 15 kW



BL 9025 up to 11 kW

## **Function Diagram**



- · Softstart and softstop function
- · 2-phase control
- For motors up to 15 kW at 3 AC 400 V
- Acceleration and deceleration time resp. starting and switch-off torque are separately adjustable
- Wide input voltage range of the power semiconductors
- Galvanic isolation of control input with wide voltage range up to AC/DC 480 V control input
- 3 auxiliary voltages at the device up to AC 230 V
- Integrated overtemperature monitoring
- LED indication
- According to EN 60 947-4-2
- 90 mm width

### Additional Information about this topic

For motors up to  $5.5~\mathrm{kW}$  we recommend the softstarter BA 9018 or BA 9019.

#### **Approvals and Marking**



### **Applications**

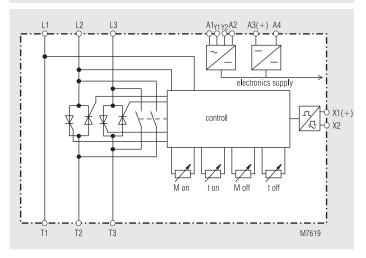
- · Motor with gear, belt or chain drive
- Fans, pumps, conveyor systems, compressors
- Packaging machines, door-drives
- Start current limiting on 3-phase motors

## Function

Softstarters are electronic devices designed to enable 1-phase or 3-phase induction motors to start smoothly. The devices slowly ramps up the current on two phases, therefore allowing the motor torque to build up slowly. This reduces the mechanical stress on the machine and prevents damage to conveyed material.

When the motor is up to full speed the semiconcutors in the device are bridged to prevent internal power losses and heat build up. In addition the device allows a softstop function prolonging the stop time of the motor, preventing high counter torques from abruptly stopping the motor.

# **Block Diagram**



#### Indication

green LED: on, when supply connected - on, when semiconductors bridged vellow LED: - flashing during ramp up or down red LED: Continuously on: Temperature fault Flashing: Attention: Phase reversal

#### **Notes**

Variation of speed is not possible with this device. Without load a softstart cannot be achieved. It is recommended that the softstart is protected by superfast semiconductor fuses rated as per the current rating of the softstart or motor. However, standard line and motor protection is acceptable, but for high starting frequencies motor winding temperature monitoring is recommended.

The softstarter must not be operated with capacitive load e.g. power factor compensation on the output.

#### **Technical Data**

Nominal voltage: 3 AC 200 V - 15 % ... 480 V + 15 %

Nominal frequency: 50 / 60 Hz

	BI 9025	BL 9025
Width:	90 mm	90 mm
Nominal motor power P <sub>N</sub> at		
480 V:	18.5 kW	15 kW
400 V:	15 kW	11 kW
200 V:	7.5 kW	5.5 kW
Nominal current I <sub>N</sub>	32 A	25 A
Switching frequency	30 / h	10 / h
at 3 x $I_N$ , 10 s, $\vartheta_H = 45^{\circ}$ C:	30 / 11	10 / 11
Time between ž starts	min.110 s	min. 350 s

approx. 0.1 P<sub>N</sub> Min. motor power: Start torque: 30 ... 80 % Ramp time: 1 ... 10 s Deceleration torque: 30 ... 80 % Deceleration time: 1 ... 20 s Recovery time: 200 ms

Auxiliary voltage:

A1/A2, AC 115 V +10%, -15%: bridge A1 - Y1

bridge A2 - Y2

bridge Y1 - Y2 A1/A2, AC 230 V +10%, -15%: A3/A4, DC 24 V +10%, -15%: polarity protected

Power consumption: . 3 W Residual ripple: 5 %

Semiconductor fuse: 50 A superfast

**Control Input** 

AC/DC 24 - 480 V Voltage range X1/X2:

> 20 V Softstart: Softstop: < 5 V

**General Data** 

0 ... + 40°C Temperature range:

It is possible to operate the unit at 40°C ... 60°C, the number of starts per

hour must then be reduced by 1.5 % / °C temperature increase.

Storage temperature: - 25 ... + 75°C

Usage category: according to EN 60 947-4-2, AC-53 b

Clearance and creepage

distances

rated impuls voltage / pollution degree

Control voltage to auxiliary

voltage, motor voltage: IEC 60 664-1 6 kV / 2

Auxiliary voltage to

4 kV / 2 motor voltage: IEC 60 664-1

#### **Technical Data**

**FMC** 

Electrostatic discharge: 8 kV (air) IEC/EN 61 000-4-2 HF-irradiation: 10 V/m IEC/EN 61 000-4-3 Fast transients: 2 kV IEC/EN 61 000-4-4 Surge voltages

between

wire for power supply: 1 kV IEC/EN 61 000-4-5 between wire and ground: 2 kV IEC/EN 61 000-4-5

Degree of protection

Housing: IP 40 IEC/EN 60 529 Terminals: IP 20 IEC/EN 60 529 Vibration resistance: Amplitude 0.35 mm IEC/EN 60 068-1

frequency: 10 ... 55 Hz

0 / 055 / 04 IEC/EN 60 068-1 Climate resistance:

Wire connection

Load terminals: 1 x 10 mm<sup>2</sup> solid 1 x 6 mm<sup>2</sup> stranded ferruled

Control terminals: 1 x 4 mm<sup>2</sup> solid or

1 x 2.5 mm<sup>2</sup> stranded ferruled (isolated)

2 x 1.5 mm<sup>2</sup> stranded ferruled (isolated)

DIN 46 228-1/-2/-3/-4 or 2 x 2.5 mm<sup>2</sup> stranded ferruled

DIN 46 228-1/-2/-3

Wire fixing

Control terminals:

Load terminals: Plus-minus terminal screws M4

box terminals with wire protection Plus-minus terminal screws M3.5 box terminals with wire protection

Mounting: DIN rail mounting IEC/EN 60 715

Weight BI 9025:

870 g BL 9025: 835 q

**Dimensions** 

Width x height x depth: 90 x 85 x 121 mm

## **Standard Type**

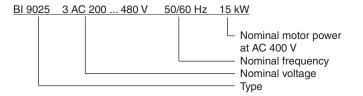
BL 9025 3 AC 200 ... 480 V 50/60 Hz 11 kW Article number: 0050957

3 AC 200 ... 480 V Nominal voltage:

Nominal motor power

at AC 400 V: 11 kW Width: 90 mm

### **Odering Example**



## **Control Input**

If a voltage of more than 20 V is connected to terminals X1/X2, the device begins with softstart. If the voltage falls lower than 5 V the device will softstop.

### **Adjustment Facilities**

Potentiometer	Description	Initial setting
$M_{on}$ $t_{on}$ $M_{off}$ $t_{off}$	Starting voltage Ramp-up time Deceleration torque Deceleration time	fully anti-clockwise fully clockwise fully clockwise fully clockwise

### **Set-up Procedure**

Set potentiometer "M<sub>on</sub>" to minimum (fully anti-clockwise).
Set potentiometer "M<sub>off</sub>" to maximum (fully clockwise).
Set potentiometer "t<sub>off</sub>" to maximum (fully clockwise).
Set potentiometer "t<sub>off</sub>" to maximum (fully clockwise).
Start the motor and turn potentiometer "M<sub>on</sub>" up until the motor starts to turn without excessive humming.

Stop the motor and restart.

Adjust potentiometer "to give the desired ramp time.

Stop and restart the motor.

 $\stackrel{\cdot}{\text{Adjust}}$  potentiometer " $\text{M}_{\text{off}}$ " until the motor starts to visibly slow down at the initation of the softstop cycle.

Stop and restart the motor.

Adjust potentiometer "t<sub>off</sub>" to give the desired deceleration time. Stop and restart the motor, readjusting the potentiometers until the desired starting/stopping characteristics are achieved.

During softstop the device must be connected to the 3-phase system.

- Attention: If the ramp-up time is adjusted to short, the internal bridging contact closes before the motor is on full speed.

This may damage the bridging contactor or bridging relay.

#### **Temperature Monitoring**

BH/BL/BI 9025 features overtemperature monitoring of its internal power semiconductors. When the safe running temperature is exceeded the power semiconductors will turn off and a red LED on the front of the unit will illuminate. BI/BL 9025 can be reset after the semiconductors have cooled down by momentarily removing the auxiliary supply voltage. An LED indicates the fault (see fault detection).

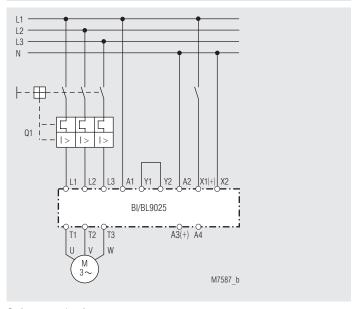
### **Safety Instructions**

- Never clear a fault when the device is switched on
- Attention: This device can be started by potential-free contact, while connected directly to the mains without contactor (see application example). Please note, that even if the motor is at rest, it is not physically separated from the mains. Because of this the motor be disconnected from the

mains via the corresponding manual motor starter. The user must ensure that the device and the necessary components are mounted and connected according to the locally applicable regulations and technical standards.

Adjustments may only be carried out by qualified specialist staff and the applicable safety rules must be observed.

# **Connection Example**



Softstart and softstop Phase: 3 AC 400 V

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